LiveDevices
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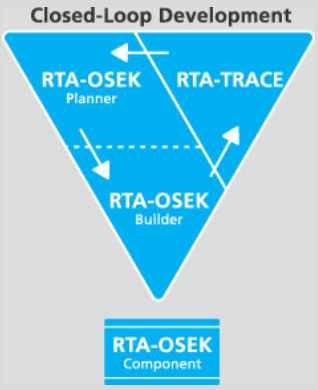
RTA-OSEK

Motorola Star12x with the Cosmic Compiler



Features at a Glance

- OSEK/VDX OS version 2.2 certified OS
- RTOS overhead: 12 bytes RAM, 92 bytes ROM
- Category 2 interrupt latency: 19 CPU cycles
- Applications include: HEVAC, engine management, security, integrated starter alternators

RTA-OSEK

RTA-OSEK provides an application design environment that combines the smallest and fastest OSEK RTOS with an unique timing analysis tool.

This port data sheet discusses the Motorola Star12x port of the RTA-OSEK kernel alone and should be read in conjunction with the Technical Product Overview "*Developing Embedded Real-Time Applications with RTA-OSEK*" available from LiveDevices.

The kernel element of RTA-OSEK is a fixed priority, pre-emptive real-time operating system that is compliant to the OSEK/VDX OS standard version 2.2 for all four conformance classes (BCC1, BCC2, ECC1 and ECC2) and intra processor communication using OSEK COM Conformance Classes A and B (CCCA and CCCB).

All CPU overheads of the kernel have low worst case bounds and little variability in execution time. The kernel is particularly suited to systems with very tight constraints on hardware costs and where run-time performance must be guaranteed.

The kernel is configured using an offline tool provided with RTA-OSEK. Determining in advance which features are used allows memory requirements to be minimized and API calls to be optimized for greatest efficiency.

All tasks and ISRs in RTA-OSEK run on a single stack – even extended tasks. This allows dramatic reductions in application stack space requirements.

The RTA-OSEK kernel is designed to be scalable. When a task uses queued activation or waits on events, the additional RTOS overhead required to support these features is paid by the task rather than by the system. This means that a basic single activation task uses the same resources in a BCC1 system as it does in an ECC2 system.

Compiler/Assembler/Linker

The libraries containing the code for the RTA-OSEK kernel have been built using the following tools:

- Cosmic cxs12x Version V4.6a
- Cosmic cxs12x Version V4.6a
- Cosmic clnk Version V4.4i

Memory Model

The HC12X/COSMIC supports a special page-zero addressing, but conventionally low addresses are used for I/O flags. RTA-OSEK makes no special use of page zero, and the modifier @dir is not used.

The use of program bank-switching for application code is supported. All library code has been compiled without the @far modifier, and must therefore appear in unbanked pages. Application code may be placed in banked pages, and may use all API calls including those entail a bank switch.

ORTI Debugger Support

ORTI is the OSEK Run-Time Interface that is supported by RTA-OSEK for the following debuggers:

- iSYSTEM winIDEA

Further information about ORTI for RTA-OSEK can be found in the ORTI Guide.

Hardware Environment

RTA-OSEK supports all variants of the Motorola Star12X family.

Interrupt Model

8 levels of interrupts are supported.

Floating Point Support

This port of the RTA-OSEK component is designed to work with fully re-entrant software floating-point libraries supplied by Cosmic. This allows floating-point to be used in RTA-OSEK tasks and ISRs without the need to save and restore any additional context.

Evaluation Board Support

This port of RTA-OSEK can be used with any Motorola Star12X evaluation board. An example application is provided to run on the QFP112 EVB evaluation board. This application can be adapted for other target boards by adjusting the linker command file (eg, to alter the allocation of program sections) and one source file (if alternative output pins are required).

Functionality

The below table outlines the restrictions on the maximum number of operating system objects allowed by RTA-OSEK.

Note that OSEK specifies that queued activations in an ECC2 system are only possible for basic tasks. Where tasks share a priority level, the maximum number of queued activations per priority level is 255.

	BCC1	BCC2	ECC1	ECC2
Max no of tasks	16 plus an idle task			
Max tasks per priority	1	16	1	16
Max queued activations	1	255	1	255
Max events per task	n/a	n/a	16	16
Max nested resources	255			
Max alarms	not limited by RTA-OSEK			
Max standard resources	255			
Max internal resources	not limited by RTA-OSEK			
Max application modes	255			

The number of alarms, tasksets, schedules and schedule arrivalpoints is only limited by available hardware resources.

Memory Usage

The memory overhead of RTA-OSEK is:

Memory type	Overhead (bytes)
RAM	12
ROM/Flash	92

In addition to the RTOS overhead, each object used by an application has the following memory requirements:

Object	RAM Bytes	ROM Bytes
BCC1 task	0	17
BCC2 task	5	24
ECC1 task	11	29
ECC2 task	13	33
Category 1 ISR	0	0
Category 2 ISR	0	25
Resource	0	10
Internal Resource	0	0
Event	0	2
Alarm	5	29
Counter	2	11
Taskset (RW)	2	2
Taskset (RO)	0	2
Schedule	7	16
Arrivalpoint (RW)	6	6
Arrivalpoint (RO)	0	6

In addition to these static memory requirements each task priority and Category 2 interrupt has a stack overhead (in addition to application stack usage). The single stack model means that this overhead applies to each priority level rather than to each task. Similarly, for Category 2 interrupts this overhead applies for each unique interrupt priority. The below table shows stack usage for these objects.

Object	Stack Bytes
Task priority level	18
Category 2 interrupt	12

RTA-OSEK provides an optimization for task termination if the user can guarantee that tasks only terminate from their entry function. Tasks that terminate from elsewhere are not eligible for this optimization and duly require 7 more stack bytes per priority level than indicated in the table above.

Performance

The following table gives the key kernel timings for operating sys-

tem behavior in CPU cycles.

Task Type	Basic	Extended	Ref
Category 1 ISR Latency	19	19	K
Category 2 ISR Latency	19	19	A
Normal Termination	63	147	D
ChainTask	144	316	J
Pre-emption	129	218	C
Triggered by alarm	221	310	F
Schedule	111	197	Q
ReleaseResource	128	214	M
SetEvent	n/a	375	S
Category 2 exit switch latency	95	181	E

All performance figures are for the non-optimized interface to RTA-OSEK. Using the optimized interface will result in shorter execution times for some operations. All tasks use lightweight termination and no pre or post task hooks were specified.

The execution time for every kernel API call is available on request from LiveDevices.

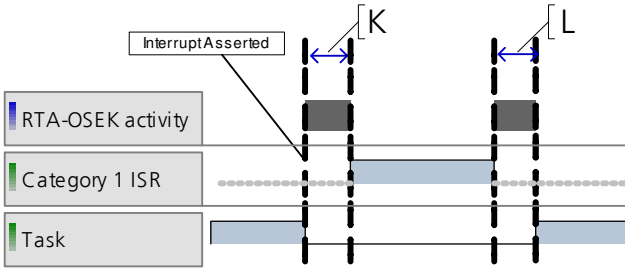


Figure 1 - Category 1 interrupt with return to interrupted task

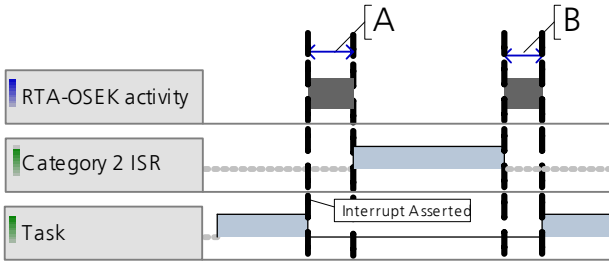


Figure 2 - Category 2 interrupt with return to interrupted task

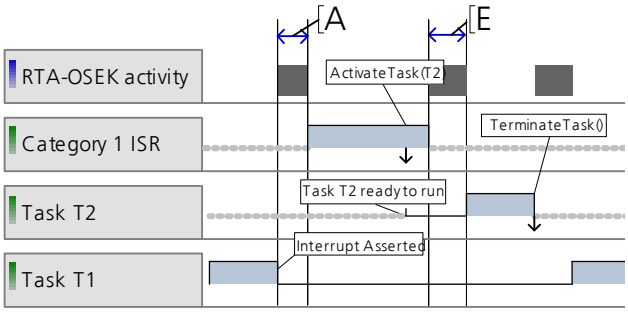


Figure 3 - Category 2 interrupt activates a higher priority task

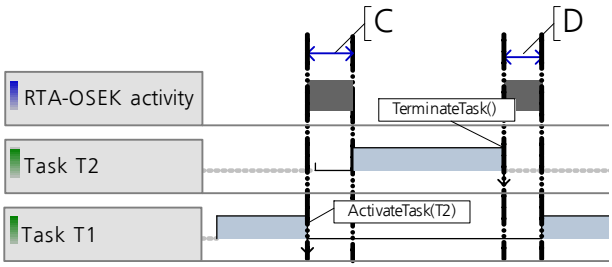


Figure 4 - Task activates a higher priority task

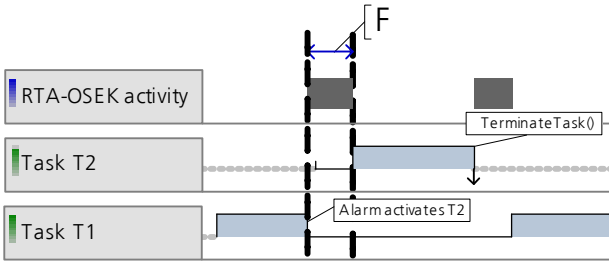


Figure 5 - Alarm activates task

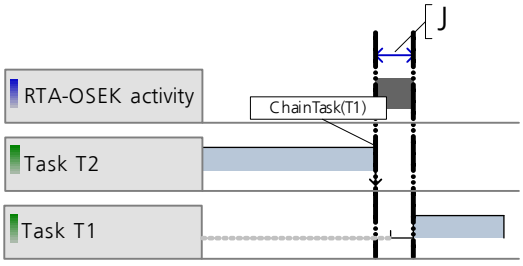


Figure 6 - Task chaining

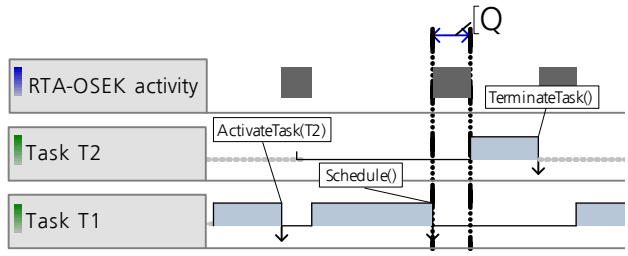


Figure 7 - Schedule() call

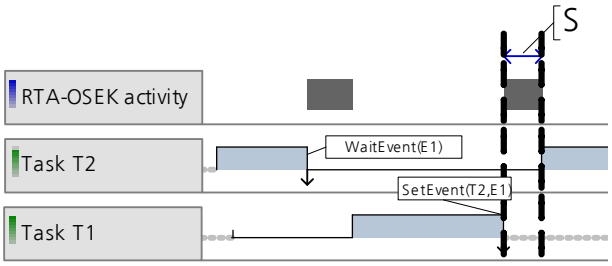


Figure 8 - Activation by SetEvent()

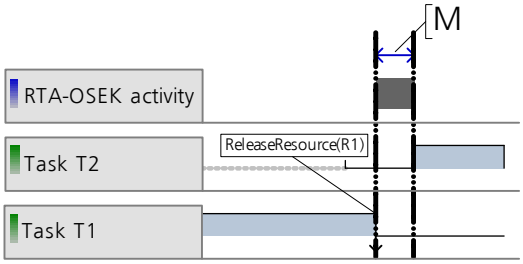


Figure 9 - ReleaseResource()

Benchmarks

The following sections shows benchmarks for RTA-OSEK memory usage for BCC1, BCC2, ECC1 and ECC2 conformant applications. The applications have the following framework:

- 8 tasks plus the idle task
- All basic tasks are lightweight tasks
- 1 Category 2 ISR with a 10ms minimum inter-arrival time
- 1 Counter
- 7 or 8 alarms, all attached to the same counter
- No resources or internal resources
- No hooks
- No schedules
- No tasksets
- Built using standard status

The following table shows the task priority configuration for each benchmark application:

Task/ISR	Stack (bytes)	Period (ms)	BCC1	BCC2	ECC1	ECC2
ISR1	10	10	IPL1	IPL1	IPL1	IPL1
A	10	10	8	8	8	8
B	20	20	7	7	7	7
C	30	20	6	6	6	6
D	40	30	5	5	5	5
E	50	50	4	4	4	4
F	60	80	3	3	3	3
G	70	100	2	2	2	2
H	80	150	1	1	1	2
Idle	10	-	idle	idle	idle	idle

The overhead figures give the ROM and RAM required for RTA-OSEK in addition to that required by the application. The RAM figure is shown split into RAM data and RAM stack.

BCC1

The BCC1 application uses 8 basic tasks with unique priorities.

This application has the following overheads:

Memory usage	Bytes
OS ROM	**985**
OS RAM	**210**
comprising RAM data	54
comprising RAM stack	156

BCC2

The BCC2 application uses 8 basic tasks with unique priorities.

Tasks A-G are attached to 7 alarms. Task H is activated multiple times from Task A and has maximum queued activation count of 255.

This application has the following overheads:

Memory usage	Bytes
OS ROM	**1163**
OS RAM	**210**
comprising RAM data	52
comprising RAM stack	158

ECC1

The ECC1 application uses 7 basic tasks and 1 extended task with unique priorities. Task H is the extended task and it waits on a single event that is set by basic tasks A-G.

This application has the following overheads:

Memory usage	Bytes
OS ROM	**1495**
OS RAM	**230**
comprising RAM data	65
comprising RAM stack	165

ECC2

The ECC2 application uses 6 basic tasks and 2 extended tasks. Tasks G and H are the extended tasks and share a priority. The extended tasks wait on a single event that is set by tasks A-F.

This application has the following overheads:

Memory usage	Bytes
OS ROM	**1972**
OS RAM	**274**
comprising RAM data	84
comprising RAM stack	190

Stack Optimization

Using stack optimization with the benchmark example identifies that the following tasks can share internal resources:

"Tasks A, B and C

"Tasks D, E and F

"Tasks G and H

The benefit of this optimization is shown in the following table:

Total Stack Space (bytes)	BCC1	BCC2	ECC1	ECC2
Non-optimized	**536**	**538**	**545**	**570**
OS Overhead	156	158	165	190
Application Overhead	380	380	380	380
Optimized	**246**	**246**	**255**	**255**
OS Overhead	66	66	75	75
Application Overhead	180	180	180	180

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